	VEV
Name	LE1

Instructions: Show all work. Answer each question as completely as possible. Use exact values (yes, that means fractions!).

1. Find the steady-state vector of the stochastic matrix $A = \begin{bmatrix} .4 \\ .6 \end{bmatrix} \cdot \begin{bmatrix} .2 \\ .8 \end{bmatrix}$ by hand. You may verify your results in your calculator, but you must show work.

$$\frac{.6 \times 1}{.6} = \frac{.2 \times 2}{.6}$$

$$\vec{\chi} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \Rightarrow \vec{g} = \begin{bmatrix} \chi_4 \\ \chi_4 \end{bmatrix}$$

2. Solve the dynamical system $A = \begin{bmatrix} 1.7 & -0.3 \\ -1.2 & 0.8 \end{bmatrix}$. Classify the origin as an attractor, repeller or a saddle point. Sketch the eigenvectors on the graph, and plot several possible trajectories.

$$\lambda^2 - 2.5\lambda + 1 = 0$$

$$2.5 \pm \sqrt{6.25-4} = 2.5 \pm \sqrt{2.25} = 1.25 \pm 1.5$$

$$2 \cdot 75, -.25$$
Origin is Saddle point
$$-1.05 \times 1 -.3 \times 2 = 0$$

$$\times_1 = -\frac{7}{4} \times 2$$
3. Solve the differential equation $\vec{x}' = \begin{bmatrix} -3 & 2 \\ -1 & -1 \end{bmatrix} \vec{x}$, by finding and plotting the eigenvectors, characterizing the origin as an attractor and the contact of the contact of

$$-1.05 \times_1 - .3 \times_2 = 0$$

 $X_1 = -4 + \times_2$

characterizing the origin as an attractor, repeller or saddle point, and writing the general solution of the system. Plot several sample trajectories on your graph.

$$(-3-)(-1-)+2=0$$

 $3+3++++^2+2=0$
 $+4++5=0$

$$\begin{bmatrix}
-3+2+i & 2 \\
-1 & -1+2+i
\end{bmatrix} = \begin{bmatrix}
-1+i & 2 \\
-1 & 1+i
\end{bmatrix}$$

$$-X_1 + (1+i)X_2 = 0$$

(Hi)
$$x_2 = x_1$$
 $\hat{\vec{x}} = \begin{bmatrix} 1+i \\ 1 \end{bmatrix}$ $\hat{\vec{x}} = \begin{bmatrix} 1-i \\ 1 \end{bmatrix}$ Spenals in

$$\lambda = \frac{-4 \pm \sqrt{16-20}}{2} = -2 \pm i$$

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$$e^{-2 \pm i)t} = e^{-tt} (\cot t + i \sin t) + c_1 \left[\frac{1+i}{i}\right] e^{-tt} (\cot t - i \sin t)$$